MOS[®]

Conclusions

In conclusion, TSN protocols provide an efficient way for industrial systems to communicate. Our proof of concept application has shown that a physical system can relay and react to information quickly using a just partial TSN. In the future to build upon this project MSRP can be added in order to get full TSN functionality working.



Industrial Application of Time Sensitive Networking Parker Berberian, Nick Kahn, Greg Wojtas, Computer Science, University of New Hampshire

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A rope is fixed between two industrial motors. When spinning at the right speeds the rope can form nodes, like a jump rope.

Motors that don't talk to each other lose sync and lose nodes. Could communicate over IP, but need TSN to guarantee communication and share a clock. To add TSN, add control nodes (xMOS boards) Control nodes bridge network communication to motor control. Add in control node with common industrial control algorithm for sync,, commands and feedback guaranteed communications with shared clock!

Motor Encoder

GPIO Driver

get_speed()

TSN Protocols

Ethernet Driver

GPTP

Mean Propagation Delay = ((T2 - T1) - (T4 - T3))/2• Used to find the amount of time a message takes to travel through the medium Correction Field = PropDelay + ResidenceTime + TransmissionTime + Prior CorrectionField

• Used to help sync the time between the two different clocks TimeSync = OriginTimeStamp + PropDelay + CorrectionField + transmissionTime



Motor

Driver

xMos

Regular computer networks can slow down unexpectedly, and this can cause issues for time sensitive applications. Time sensitive networking protocols serve to provide guaranteed throughput and latency over a regular Ethernet network, eliminating this problem.

An existing application of TSN can be found in the audio / visual industry. It is very important that the speakers at opposite ends of a concert hall play the correct sounds at the correct time. Even slight delays in the signal can reduce sound quality significantly. This project is a proof of concept application of existing TSN protocols to an industrial system, where sensor data must be communicated and reacted to in real time.

Motor

Driver

I^2C Driver

set_speed()

PID Loop

Master Node





Sponsored by the IOL Project supervisor Bob Noseworthy