# **Searching with Distributional Heuristics**

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# **Reason Under Uncertainty**

### **bounded suboptimal**:

- cost bound
- probability of finding goal within bound under given node

### anytime:

which node will lead to better solutionsearch effort under given node to goal

#### contract:

cost-to-go under given nodesearch effort under given node to goal

### **Contract Search**

### Objective:

- return best solution possible, subject to absolute time (or expansion) bound.
   Current SotA:
- Deadline-Aware Search (Dionne et al. SoCS-11) is a best-first, priority queue based contract search algorithm that must estimate two unknowns:

 $\hat{d}$ : error-corrected distance-to-go

# **Related Problems**

**Bounded Suboptimal**: Fickert et al. (AAAI-22) formulate the work of bounded suboptimal search as comparing two distributions:

 $B_{cost}(n)$ : solution cost under n $B_{bound}$ : the cost bound itself

 $\dots$  but their best algorithm, RR-d, uses unprincipled round-robin queue alternation.

• Can uncertainty help decide proper strategy? Anytime: Thayer et al. (SoCS-12) defined

In order to reason under uncertainty:
need better measures of uncertainty
need to better exploit those measures

New Distributional Heuristic

A rational search algorithm should prefer:

low uncertainty when heuristic is lowhigh uncertainty when heuristic is high

Heuristic belief variance can be assumed from single-step error (Fickert et al. IJCAI-21) but requires hyperparameter

New: *h<sub>FFrand</sub>* 

• don't assume, measure!

- parameterless distributional heuristic
- randomizes tie-breaking in FF

distribution estimation via sampling
see comparison below with other heuristics for start state of IPC benchmarks (Wissow & Asai 2022, unpublished collaborative work)  $\Delta e$ : average expansion delay

DAS also pathologically prunes all open nodes as unreachable—room for improvement! Our Deadline-Aware Beam Search (DABS):

• dynamically adjusts width of parallel hill-climbing

ullet only needs to estimate  $\hat{d}$ 

# DABS beats DAS and ARA\*:



anytime objective as minimizing time between solutions, but this definition is incomplete:

an anytime algorithm also performs better than another by returning lower cost solutions, even if on the same solution schedule.

• Can uncertainty help balance earlier solutions with better ones?

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 $h_{FFrand}$ : 10 different seeds per problem (sorted within domain by  $h_{FF}$ )

400 -					*			$ \begin{array}{c cc} \times & h^* \\ \hline & & h_{Imcut} \\ \hline & & h_{ff} \\ \hline & & \pm 2\sigma (h_{FFrand}) \\ \hline & & \bar{h}_{FFrand} \end{array} $
300 -								
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