

## INTRODUCTION

The UNH Pedicab Project is a Mechanical Engineering Student lead project that involves the designing and manufacturing of a pedicab. The idea for building the the pedicab project is the theory of "reciprocity" and meant to align with the goals of the United Nations Sustainable Goals. We believe that a community that supports one another creates a positive environment for everyone. The operator will provide a positive experience (aka. a free ride) to the community in hopes that the community will perform a kind gesture to someone else without asking. The pedicab will be a new carbon-neutral mode of transportation throughout the seacoast region of New Hampshire providing a fun and eco-friendly way to get around.

#### Design Criteria

- Frame Composed of A513 High Carbon Steel
- TIG Welded
- Made of 2x2",1x1", & 1.5x1.5" Tube Stock.
- Modeled in SOLIDWORKS & MARC.
- Maximum deflection of 2.5mm.
- F.O.S. of 2.0.
- Less than 200 lbs.

### SUSPENSION

- The pedicab suspension was simulated as a Second Order Mass, Spring Damper System.
- Used a piezoelectric crystal and applied an impulse load to determine the vertical acceleration of the shocks.
- Data was integrated with MATLAB to model the time constant ( $\tau$ ), damping ratio( $\zeta$ ), and system  $gain(\kappa)$ .









# **UNH Positive Pedicab 2022-2023** Mechanical Engineering Department, University of New Hampshire Derek Jackson, Jalen Galan, David Pekkala, Brett Goldstein, Jonathan DiGiosa Project Advisors: Juan Cuevas Carlos Batista, Brent Bell

## FRAME DEVELOPMENT

- **Phase 1**: Generated Conceptual Drawings
- **Phase 2**: Developed SolidWorks model of frame
- **Phase 3**: Optimized frame to meet customer needs
- **Phase 4**: Prototyped and tested frame for failure
- **Phase 5**: Manufacturability of final prototype







### BRAKING SYSTEM

- Hydraulic Rear Brake System
- Parking Brake
- Integrated Electric Motor Kill Switch when braking
- Fluid Dynamic calculations done to validate correct hydraulic pressure under braking.

















## SIMULATIONS & RESULTS

- Static and Kinematic Analysis Performed
- reducing aerodynamics.



#### E-Bike System

- **BAFANG Mid-Drive E-Bike Motor** (70A,48V,750 W)
- 48 V Battery (48V, 14,000 mAh)
- **48-12V Direct Current Regulator**
- 6-Slot 30A Fuse Box
- 12V- Turn Signals, LED Brake Lights, LED Headlight



# SEAT COMPOSITION

- Back Rest: 54"X19"
- Bottom Cushion: 54"X16" MATERIALS
- 3 in. High Density Foam
- <sup>1</sup>/<sub>4</sub>" High-Loft Batting
- <sup>3</sup>/<sub>4</sub>" Plywood
- Navy Duck Cloth



Verified the final design of our frame using finite element analysis software's (e.g. SolidWorks and MARC student edition)

Based on our design our frame was able to be lightweight at 184 pounds but retain its integrity. It can operate at a speed of 16 mph and have comfortable ergonomics for the operator. In the future possible upgrades include PV solar panels and drag

### ELECTRONICS



